

SPECIFICATION

Product Name: LED Particle Sensor

Item: PM1006K

Version: V0.4

Date: 2018-10-5



Revision

No.	Version	Content	Date
1	V0.1	First edition	2018.03.06
2	V0.2	Adding PWM communication	2018.04.24
3	V0.3	Add temperature influence curve	2018.08.28
4	V0.4 Modify the photoelectric linear		2018.11.06

Infrared LED Particle Sensor PM1006K





Introduction

Infrared LED particle sensor module PM1006K adopts the principle of optical scattering to detect the variation trend of particle (size between 1µm to 10µm) concentration in the air. There is an infrared light-emitting diode and an optoelectronic sensor built-in PM1006K, and light rays from the light-emitting diode will be reflected when pass through the particle. The optoelectronic sensor can show the concentration of particle in the air by detecting the intensity of reflected light. Sensor can output measuring value by pulse or UART signal.

Principle

According to the scattering principle of light,

The LED light generates reflected light when meet particles. Photoelectric diode detects the light intensity of reflected light, judging the particle concentration according to pulse signal.

Photoelectric diode will output low pulse when do not detect particles. Otherwise, photoelectric diode will output high pulse when detect particles. And pulse signal is in proportion on the detected light intensity. Pulse signal will be magnified by amplifier and calculated by CPU, output measuring result finally.

Features

- ♦ Electromagnetic shielding, anti-interference
- \diamond Small volume, high accuracy
- \diamond Low coil consumption, wide measuring range
- ♦ Quick response

Applications

- ♦ Household air purifier
- ♦ Automobile air purifier
- ♦ Residential and commercial air conditioning
- ♦ HVAC system
- ♦ All kinds of IAQ monitor
- ♦ IoT hardware intelligence

Advantages

- Integrated temperature sensor, temperature compensation within the whole temperature range

Table 1. Specification

LED particle sensor specification

Principle	Light scattering(LED)	
Measuring range	0~1000µg/m³	
	$\pm 20 \mu g/m^3$ or $\pm 20\%$ of reading	
Accuracy	(@voltage 5.0V,	
	25±2°C, 50%±10%RH)	
Response time	8s	
Working	-20°C~+75°C,	
condition	0~95%RH(non-condensing)	
Store on dition	-40°C~+85°C,	
Storage condition	0~95%RH(non-condensing)	
Working voltage	DC 5V±0.2V ripple <50mV	
Working current	≤30 mA	
Signal output	UART: 4.5V level; PWM	
Size	W46.2*H34.1*D18 mm	
MTTF	≥5 year	



Internal architecture and principle description

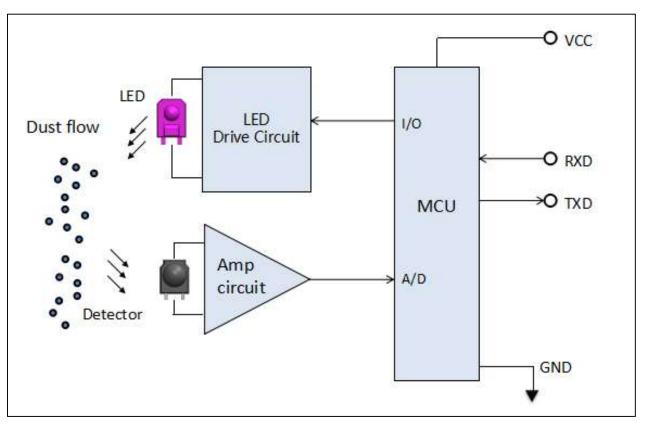


Fig 1 Internal architecture

Light scattering principle

According to the above picture, the light source of PM1006K is consist of LED which launch to detecting particles light, front-loading lens and drive circuit. The detecting part is consist of postposition condensing lens, photoelectric part which receives reflected light and amplifying circuit.

The particle measuring principle of PM1006K

The LED light generates reflected light when meet particles. Photoelectric diode detects the light intensity of reflected light, judging the particle concentration according to pulse signal. Electronic signal is disposed by filter circuit and MCU, it will convert into PWM signal output.



I/O definitions and connectors

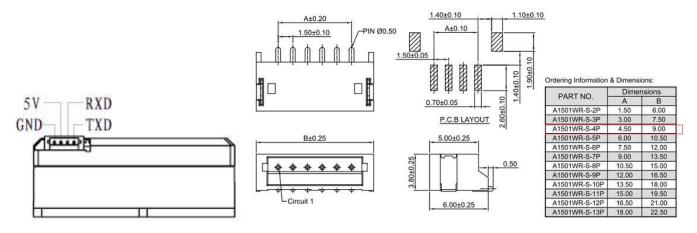


Fig 2 Connector Dimensions

Table	2.	I/O	definitions
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NO.	Pin	Description	
1	GND	Power input (ground terminal)	
2	VCC	Power input(+5V)	
3	RXD	UART receiving (TTL level @4.5-5V)	
4	TXD/PWM	UART sending (TTL level @4.5V)	

Table 3.Connector description

Item	Pin space
A1501WR-S-4P	1.5mm pitch



Photoelectric linear

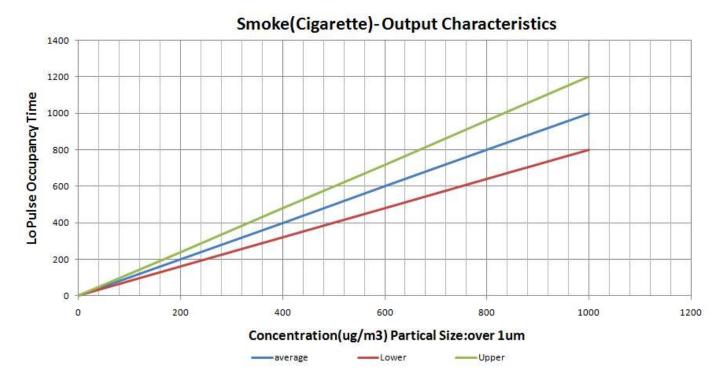


Fig 3 Photoelectric linear

• The linear curve of the sensor is verified in the following conditions:

The temperature of the environment is 25 ± 2 °C

The humidity of the environment is $50\pm10\%$ RH

Cigarette smoke: Hong Ta Shan 8mg



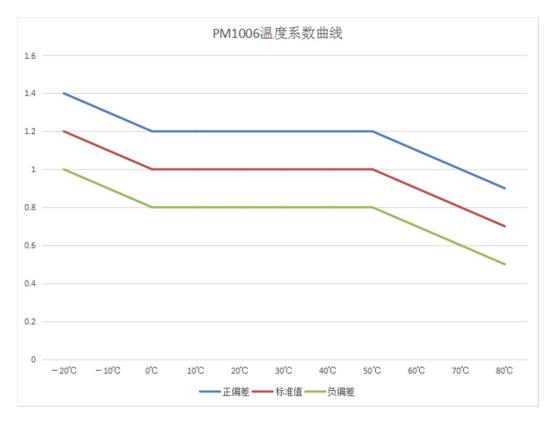


Fig 3 Temperature influence curve

- ♦ Normal temperature measuring error: 25°C±2°C, 50±10%RH, 0~1000µg/m³.
- ✤ The consistency of PM2.5 is ±20% of reading or ±20µg/m³, use the max value (TSI-8530, cigarette smoke)

Communication protocol



◆UART communication:

UART level range

-UART RX: 0~5.0V data input -UART TX: 0~4.5V data output **UART configuration** -data bit: 8 -Stop bit: 1

-Check bit: non

-Baud rate: 9600bps

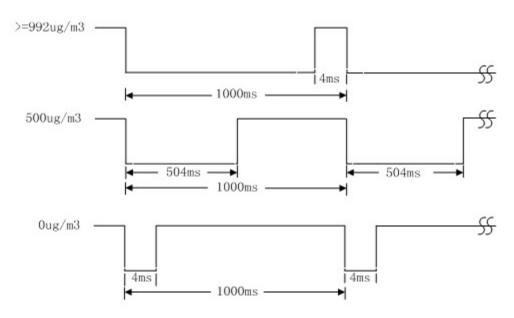
Read measures result of particles:

Send: 11 01 02 EC Response: 16 0d 02 DF1- DF4 DF5- DF8 DF9- DF12 [CS] Note: $PM2.5(\mu g/m^3) = DF3*256+DF4$ $PM1.0(\mu g/m^3) = DF7*256^{1} + DF8$ $PM10(\mu g/m^3) = DF11*256^{1} + DF12$

PWM communication

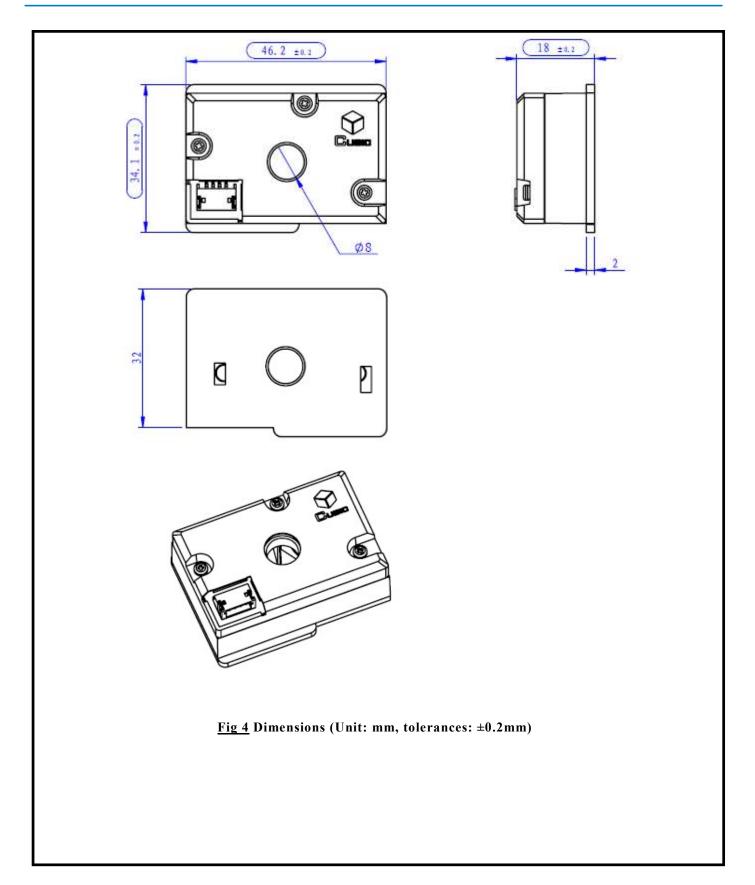
Resolution: 1ug/m3 RSP: Low potential Range: 0~992ug/m3 Cycle: 1000ms Concentration ug/m3 = low level ms - 4ms; (PWM: the minimum output low level is 4ms within 1 cycle, the concentration is 0ug/m3

PWM the max output low level is 996ms within 1 cycle, the concentration >=992ug/m3.)

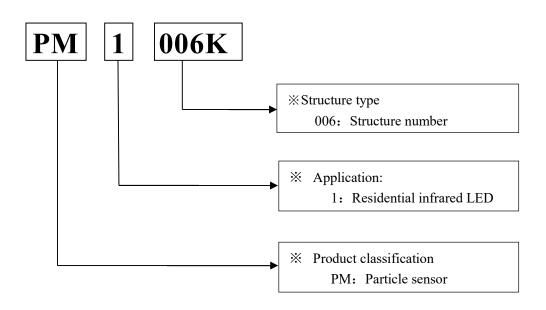




Dimensions

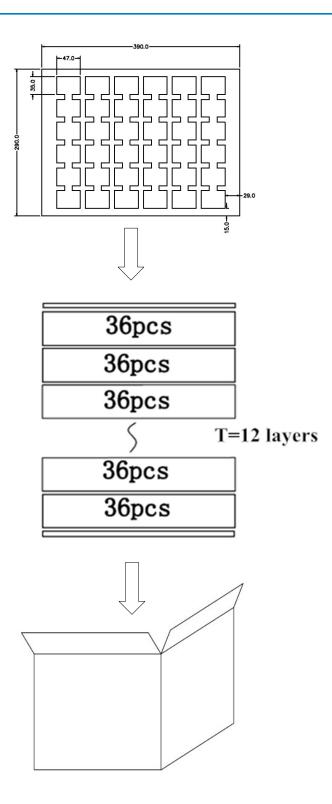








Packing



Qty per layer	Layer	Carton	Carton dimensions	Packing material
36pcs	12layers	432pcs	W400 * L300 * H320 mm	Red pearl cotton



User attention

- * Ensure the ventilation of air inlet and air outlet in installation;
- * The sensor should not be used in the environment with organic gas and flammable gas. If there is dust in the chamber of the sensor, please clean with cleaner;
- The product should be kept away from high frequency and high voltage source to avoid the interference caused by high frequency and high pressure. The measurement error of the sensor would be increased by the external light affection. Therefore, the external light should be avoided when installation;
- X The measurement error of the sensor would be increased by the irregular strenuous vibration.

After-sales services and consultancy

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